```arduino
#include <Servo.h>

Servo myservo;  // create servo object to control a servo
// twelve servo objects can be created on most boards

int pos = 0;
int buttonPin = 2;
int LEDPin = 6;

void setup() {
  myservo.attach(9);  // attaches the servo on pin 9 to the servo object
  pinMode(LEDPin, OUTPUT);
  pinMode(buttonPin, INPUT_PULLUP);
}

void loop() {
  while (digitalRead(buttonPin) == LOW) { //Run loop when button is high)
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(900);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(900);                          // wait
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(800);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(800);                          // wait
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(700);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(700);                          // wait
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(600);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(600);                          // wait
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(500);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(500);                          // wait
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(400);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(400);                          // wait
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(300);                          // wait
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    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(300);                          // wait
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(200);                          // wait
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(200);                          // wait
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(180);                          // wait
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(180);                          // wait
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(160);                          // wait
    digitalWrite(6, LOW);     // turn the LED on (LOWis the voltage level)
    delay(160);                          // wait
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(140);                          // wait
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(140);
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(120);                          // wait
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(120);
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(100);                          // wait
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(100);
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(80);                           // wait
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(80);
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(60);                           // wait
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(60);
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(40);                           // wait
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(40);
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(40);
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(40);
    digitalWrite(6, LOW);     // turn the LED on (LOW is the voltage level)
    delay(40);
    digitalWrite(6, HIGH);    // turn the LED on (HIGH is the voltage level)
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  delay(40);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(40);
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(40);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(40);
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(20);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(20);
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(20);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(20);
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(20);                          // wait
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)
  delay(20);
  digitalWrite(6, HIGH);   // turn the LED on (HIGH is the voltage level)
  delay(1000);
  digitalWrite(6, LOW);    // turn the LED on (LOW is the voltage level)

  for (pos = 0; pos <= 180; pos += 3) { // goes from 0 degrees to 180 degrees
    // in steps of 1 degree
    myservo.write(pos);                 // tell servo to go to position in variable
'pos'
    delay(15);                          // waits 15ms for the servo to reach the
position
  }
  for (pos = 180; pos >= 0; pos -= 5) { // goes from 180 degrees to 0 degrees
    myservo.write(pos);                 // tell servo to go to position in variable
'pos'

  }
}}
```